

### **Robotics Training and Competition as Novel Validation for the RxS Rating**

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Manpower, Personnel, Training & Education Information Sciences Portfolio Review

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#### Objective

 The Robotics Warfare Specialist rating, established in February 2024, is aimed at developing expertise in autonomous and robotic technologies to support the Navy's hybrid fleet initiatives.



 Specialists are trained to operate, maintain, and manage advanced robotic systems.

#### **Project Objectives:**

- Provide data to back training design decisions
- Shorten the time to stand up RW "A" School





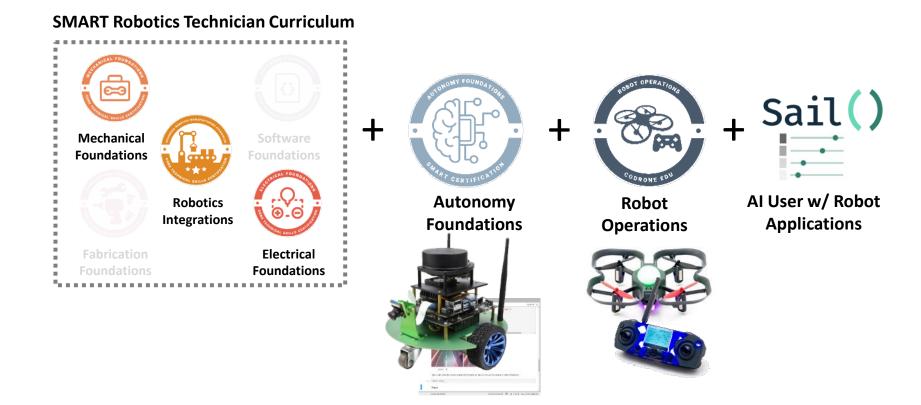
### Motivation

- The importance of robotic and autonomous systems continues to increase.
- These systems advance and replace very rapidly
  - Specializing training around single-systems scales poorly
- Carnegie Mellon University (CMU) has Robotics Technician curriculum that targets core elements of the role across industries and platforms, as well as AI-focused offerings
- But we need to know:
  - RQ1: Does training with multiple small-scale robots accelerate future learning on larger, more capable robotic platforms?
  - **RQ2:** What are the role and impact of ML/AI training for RW?



### Methodology

 Using Design-Based Research methods, adapt existing robotics technician curriculum for automotive and manufacturing into an experimental RW curriculum





#### Methodology

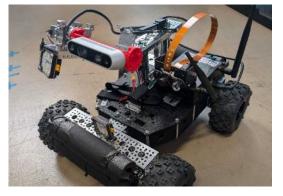
- Embed a Competition-based assessment for future platform learning potential
  - Measure ability to learn new platforms, not mastery of one now
  - Competition robotics platforms provided in collaboration with Dahlgren and Robotics/Autonomy SME's



Amphibious UGV / USV



**Kairos UAV** 

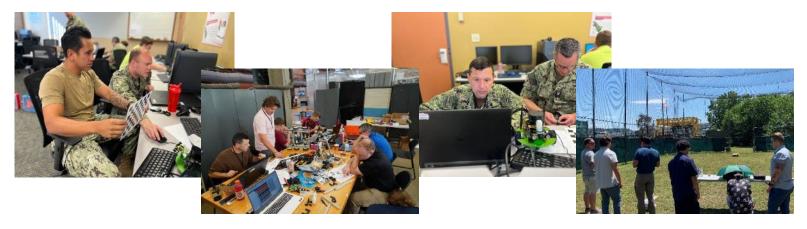


UGV w/ Advanced Perception



### Methodology

- Run test groups through the training and competition
  - Training Cohort Alpha consists of 8 Civilians and 5 Sailors
  - Plus a Competition-only comparison group with incumbent singlesystem or other "A" school training (e.g., Electronics Technician [ET])



- To avoid bias, we use an arms-length 3<sup>rd</sup> party to design the competition events and platforms
  - At a minimum, require stakeholder consensus that the competition events represent valid applications



# **Results: Adapted Experimental Curriculum - Electrical Foundations**

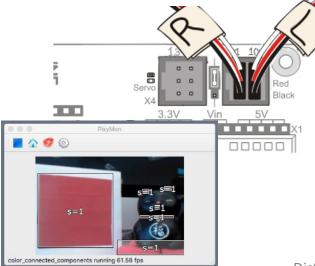
GND Arduino otor Control Boo **Electrical Foundations** focuses on the foundational concepts around basic electricity and how circuits work. Participants use multimeters to troubleshoot electrical components.

- Unit 1: Wiring and Circuits
- Unit 2: Voltage Parallel and Series Circuits
- Unit 3: Voltage and Current Motors
- Unit 4: Controlling Signals
- Unit 5: Sensors
- Unit 6: E-Panel



### **Results: Adapted Experimental Curriculum - Robotics Integration**



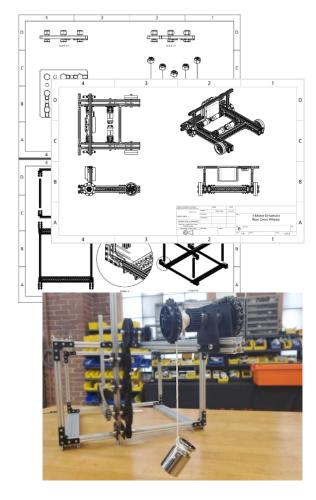


**Robotics Integration** introduces participants to situations where technicians receive multiple components of a robotics system that require assembly, installation, and debugging. Participants integrate components such as a vision sensor, breadboard, servo motors, and microprocessor.

- Unit 1: Testbed with Arduino
- Unit 2: Open-Loop Navigation
- Unit 3: Camera Integration



# **Results: Adapted Experimental Curriculum - Mechanical Foundations**

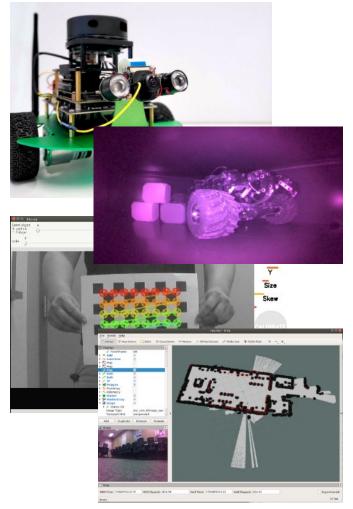


Mechanical Foundations provides participants with knowledge and hands-on experiences with a variety of tools and hardware components. By understanding the foundational mechanical principles that underpin robotics, participants develop the ability to construct and maintain these systems with increased confidence and efficacy.

- Unit 1: Strength, Stability, & Balance
- Unit 2: Transmissions & Mechanical Advantage
- Unit 3: Drivetrains
- Unit 4: Payloads



# **Results: Adapted Experimental Curriculum - Autonomy Foundations**



Autonomy Foundations equips learners with a practical understanding of how artificial shapes robotic perception and autonomy. This course provides a comprehensive foundation for operating and maintaining intelligent robotic systems.

- Unit 1: Setup
- Unit 2: Basic Navigation
- Unit 3: Basic IO and Sensing
- Unit 4: Collision Avoidance & Path Following
- Unit 5: AprilTag Navigation
- Unit6: SLAM



# **Results: Adapted Experimental Curriculum - Robot Operations**





**Robot Operations** is a *longitudinal course* designed to foster depth-ofcoverage within the Robotics Functional Tasks. Indoor and outdoor platforms are used which are pilotable, configurable, repairable, and programmable.

- Consists of daily ~30-minute tasks where participants perform missional operations, maintenance, troubleshooting, and reporting.
- Missional operations focus on Piloting, Setting waypoint navigation, Performing launch and recovery, Configuring sensors and payloads.



# **Results: Adapted Experimental Curriculum - AI User**



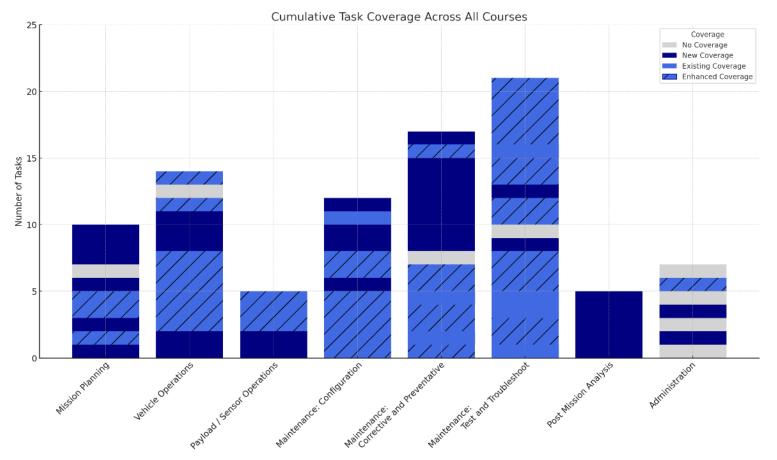
In **AI User**, participants gain knowledge and develop experience using AI/ML based systems. Participants are introduced to current applications, capabilities, and main components of AI/ML systems. Each unit is paired with an applied robotic exercise.

- Unit 1: AI Capabilities & Non-Capabilities
- Unit 2: The Role of Data
- Unit 3: Limitations, Bias, Evaluation & Troubleshooting
- Unit 4: Computing Devices and Environments
- Unit 5: Computer Vision



#### **Results: Adapted Experimental Curriculum**

• **Resulting Cumulative Course** coverage across E1-E4 Robotics Functional Tasks:

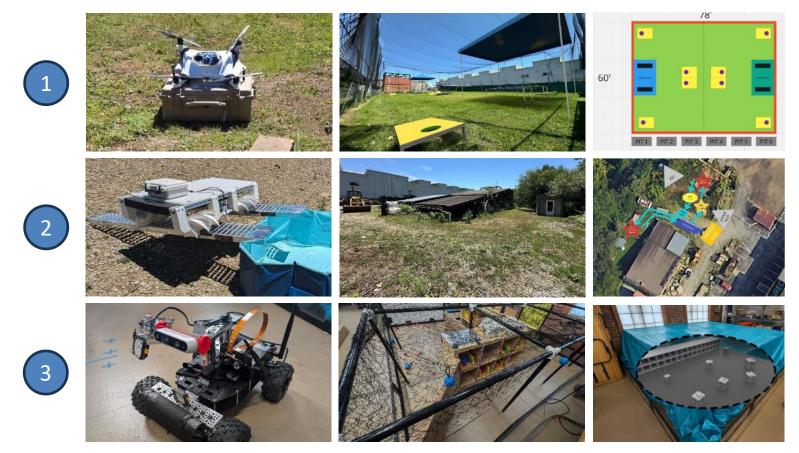


Source: Robotics Warfare Specialist Rating Establishment NEOCS Package



### **Results: Competition Design**

• Competition Designed with 3 unique platforms and events:

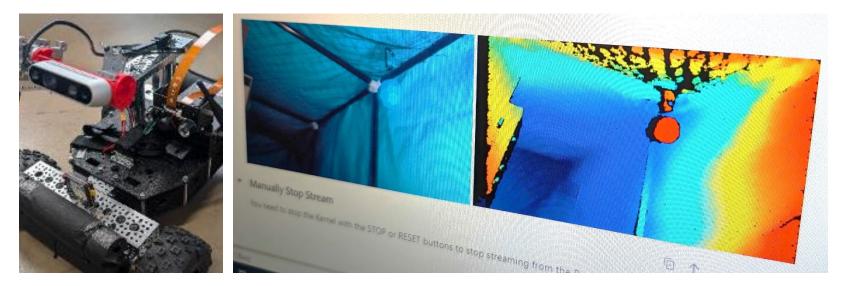


- We will be streaming the first competition test July 17 19!
  - Contact me for access to the stream or to plan a visit.



#### **UGV with Advanced Perception**

- Jetson Orin Nano with Intel RealSense Depth Camera
- Inspired by EOD UUV tasks, but altered to include SLAM and Machine Vision capabilities in a non-underwater setting





### **Results: Study in Progress**

• Currently in week 6 of 7 of Cohort Alpha!

















#### Challenges

- Initial 3<sup>rd</sup> party Competition developers fell through
- Moving target on learning objectives prior to Q3'24
- IRB/HRPO delays (resolved)
- Recruiting/attrition of community college students
- Participant logistics for a 7-week training
- Classroom technology availability and durability



### **Project Plan**

- Cohort Alpha is currently in progress
- Instrument and test curriculum revisions to follow
- Cohort Beta in planning likely Jan 2025 (FY25 Q2)



# **Conclusions & Naval Relevance**

- Testing is underway to determine the efficacy of small robot training on accelerating learning of future systems.
- Testing will also help determine the kinds of ML/AI training relevant to "optainer" roles (rather than data science ones).
- If successful, experimental curriculum could significantly shorten timeline for RW "A" school development.



#### Achievements

- Initial experimental curriculum and competition designs complete
- Achieved concurrence with key Naval stakeholders on curriculum alignment with E1-E4 RW Tasks
- IRB / HRPO Approval complete. Conducting Alpha cohort test through July 19
- Presenting at ONR Science of Autonomy Meeting (pending)



### **Questions & Contact Information**

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