

# Nanorobotic Manipulation Systems Using Nanoprobes

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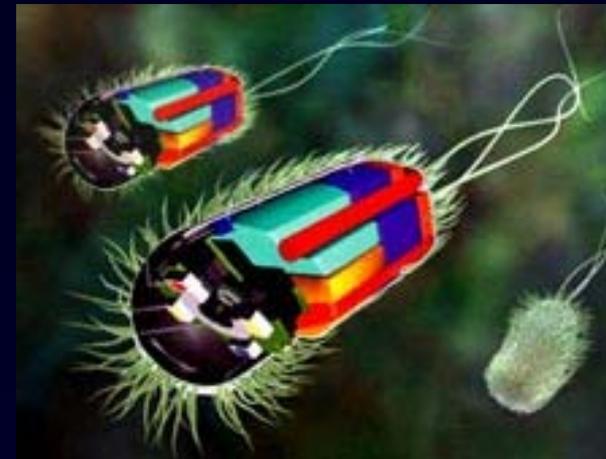
# Micro/Nano-Robotics Encompasses:

Programmable assembly and **manipulation** of micro- and nano-scale entities

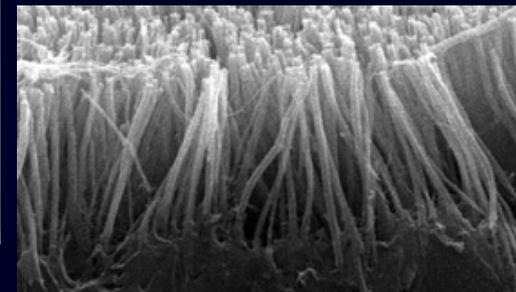
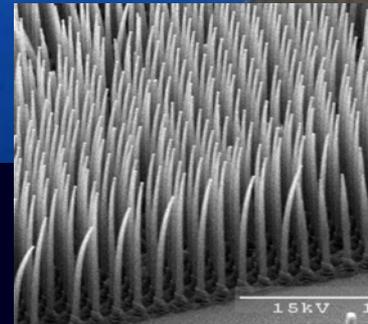
Design and fabrication of **miniature robots** down to sub-millimeter sizes

(Locomotion and dynamics dominated by the principles of micro/nano-physics)

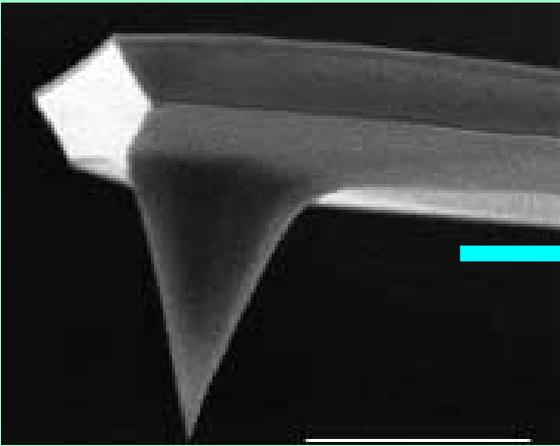
Programming and coordination of large number of these robots



# Miniature Robots @ NanoRobotics Lab



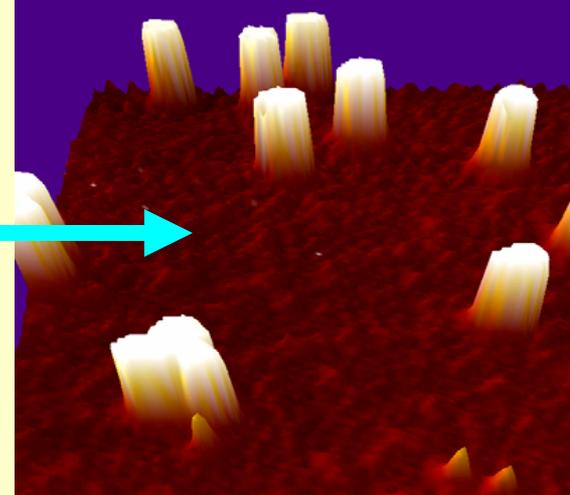
# Micro/Nano-Manipulation



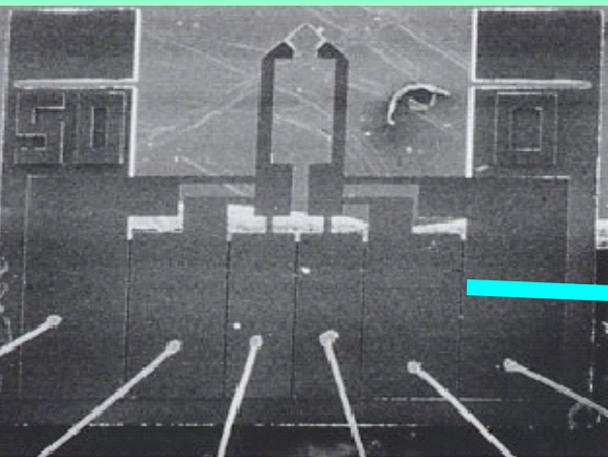
**Atomic Force  
Microscope Probes**



**Human-Machine Interface  
(Nanorobot Control)**



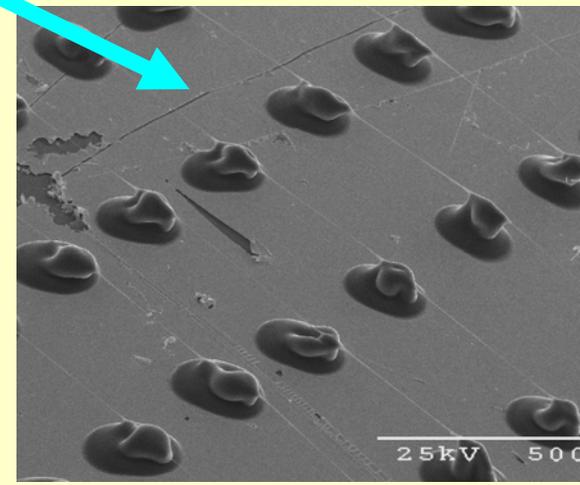
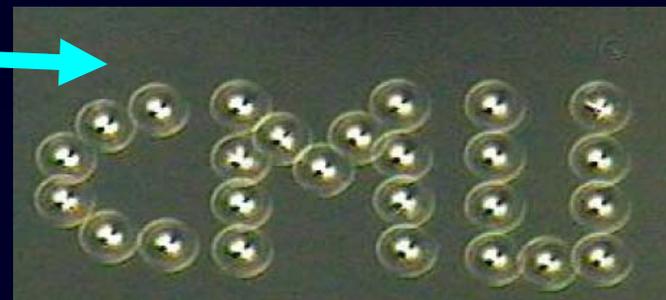
**Nanomanipulation**



**Custom Nanogrippers**



**Microassembly**



**Micro/Nanofiber Pulling**

# NanoRobotics Lab

@ Carnegie Mellon



## Graduate Students:

Burak Aksak, **ME**

Bahareh Behkam, **ME**

Cagdas Onal, **ME**

Eugene Cheung, **ME**

Steven Floyd, **ME**

Paul Glass, **BME**

Emre Karagozler, **ECE**

\*Seok Kim, **ME**

Mike Murphy, **ME**

Amrinder Nain, **ME**

Chytra Pawashe, **ME**

\*Yun Seong Song, **ME**

Bilsay Sumer, **ME**

Ozgur Unver, **ME**

## Undergraduate Students:

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Keegan, Ryan Kellogg, Eddie Lu, Chytra Pawashe,

Dave Rollinson, Will Tso, Phil Yu



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**THANKS...**