# Against theory-motivated experimentation

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### Outline

- 1. Motivation: how to choose the best next experiment?
- 2. Multi-agent model of learning through collecting and explaining the data
- 3. Evaluation of experimentation strategies:
  - a. Across contexts
  - b. Across time
  - c. With prior knowledge
- 4. Brief attempt to convince you that the results make sense
- 5. Discussion time!

## Motivation

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- 1. Are designed to test the efficiency of a particular scientific practice (e.g. replication studies: Smaldino & McElreath, 2016)
- Do not formalize active data collection, explanation, and social learning processes at the same time (e.g. the world provides all observations or the theory building is minimized, as in Zollman, 2007; Smaldino & McElreath, 2016)

#### We designed a new model

#### social learning



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"Ideal world"

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- The agents construct lower-dimensional representations (theories) to account for the evidence they collected
- The goal of each agent is to find a lower-dimensional representation (theory) that captures as much information about the higher-dimensional "ground truth" as possible

#### ground truth



social learning



#### Main questions

Which experimentation strategies work better (in general/in particular contexts)?

How much should a scientist's theoretical framework influence their experimentation?

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Confirmation

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**Disagreement (conducting crucial experiments)** 

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Novelty (space-filling)

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**Disagreement (conducting crucial experiments)** 

Novelty (space-filling)

Random

Confirmation

Falsification

**Disagreement (conducting crucial experiments)** 

Novelty (space-filling)

Random

+ hybrid strategies

# Social learning strategies

- 1. Data sharing
- 2. Feature sharing
- 3. Explanation sharing
- 4. Aligned explanation sharing
- 5. Skeptical aligned explanation sharing
- 6. Teaching and learning

+ their combinations

Group size = [5, 10]

## Ground truth

- Mixture multivariate gaussian distribution
- N of dimensions: [20, 100]
- N of clusters: [2, 10, 30]
- Agents' measurement capability:
- [all dimensions, half of the dimensions]



## Agents' explanation strategy: NN embedding

Each agent develops a lower-dimensional representation of the ground truth

Agents' theories are simple NN autoencoders with one hidden layer

N of internal neurons = [3,6]



#### "Subjective" performance

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"in-sample"

"out-of-sample"



# Experiment 1

- 1. Varying all context conditions (~4 samples per condition; 11372 simulations in total)
- 2. Looking at the learning results of the agents following different experimentation strategies at the end of the simulation (= after the group collects 300 observations)



	Subjective performance	Objective performance
better	confirmation	random
Ĩ	disagreement + confirmation	novelty
	disagreement	disagreement + falsification
	disagreement + falsification	falsification
	falsification	disagreement
	random	disagreement + confirmation
<b>▼</b> worse	novelty	confirmation

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an artifact of the simulation settings?



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Varying all conditions as in experiment 1 (4320 simulations in total)

#### objective average reconstruction error



baseline: random strategy

Let agents have some accurate prior knowledge about the ground truth

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- 1. Each agent is pretrained on 10/50/100 randomly sampled observations
- Then, agents start learning with their target experimentation strategy (the setting & all conditions are the same as experiment 1: total of 9072 simulations)

	no pre-training (naive theories)	pre-training (informed theories)
better	random	random
Ť	novelty	novelty
	disagreement +	disagreement +
	falsification	falsification
	falsification	disagreement
	disagreement	disagreement +
		confirmation
	disagreement +	falsification
₩	confirmation	
worse	confirmation	confirmation

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- 2. Within- and between-agent diversity of samples
- 3. Representativeness of samples

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+ how these change over time



### Results
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What seems to be a good approach is not always actually a good approach

Theory-motivated experimentation creates an illusion of epistemic success by introducing a bias that prevents agents from learning about the target space of phenomena

Experimentation that is uninformed by theory or previous observations (random) supports construction of the most representative accounts for the ground truth across all the studied contexts

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Generating more data that is well explained  $\neq$  learning about ground truth

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The model does not capture every kind of science

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- 1. The "active learning" strategies that scientists try to follow do not correspond to successful active learning strategies
- 2. The successful active learning strategies are fragile: they work only in very specific contexts (e.g. when a learner has accurate prior knowledge about the problem, etc). Otherwise, they are misleading.

# A theory is not a good reason to bias experimentation!



# Discussion!

- 1. Criticisms/concerns?
- 2. Scenarios where the results won't hold?
- 3. Strategies that might work better than random?

